Motion Planning of Robots

John Umstead, Daniel Weiss, Sahand Sadri, Kyle Deppe

Professor Rohit Chadha

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# 1 Efforts

(Does everything work correctly?)

# 2 Algorithms

(Algorithms, complexity of algorithms)

# 3 Contributions

John and Sahand wrote the main algorithms of the code. Kyle and Daniel contributed to writing helper functions, fixing bugs, checking for errors, and keeping GitHub organized. Daniel also wrote the readme.